

Prakruti Catherine Gogia

Computer Vision & Deep Learning Engineer

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SUMMARY

I am interested in senior software engineer and tech lead roles. I bring to the table product thinking, technical domain expertise, rapid prototyping and people management skills. I have experience building SLAM in C++ for AR. Additionally, I have led a team of hackers to ship a deep learning model using a cloud service.

WORK EXPERIENCE

Software Engineer | Microsoft HoloLens 2018–present
Core SLAM Technology

- Designed and implemented headtracking and bundle adjustment algorithms to ship [HoloLens 2](#).
- Worked on calibration, visual-inertial odometry, tracking LED constellations for new devices.
- Pioneered a 6DoF ground truth collection system using OptiTrack that provided the only source of high-fidelity and large scale data across teams. Trained vendors in calibration, data collection for new locations.

Deep Learning

- Prototyped an MC-CNN and semi-global matching-based hybrid solution for dense depth from stereo.
- Created an internal benchmark and prototyped image retrieval methods for relocalization.

Tech Lead and Co-founder | OrcaHello project [\[talk\]](#) [\[code\]](#) [\[project-page\]](#) 2019 - 2022

Led a team of 20 hackers and 2 non-profit partners to build “OrcaHello”: a 24x7 whale call detection system helping killer whale conservation in the Puget Sound. Open-sourced model, data and code.

Built the [data annotation pipeline](#) (~ 15 hrs of spectrograms tagged using active learning), trained the model, and built the live inference pipeline on Microsoft Azure (Container Instances, AKS, CosmosDB, App Service).

Won 3rd / 123 at the 2022 MSFT Hack (Hack4Good) and raised \$30K in Azure credits, \$15K in non-profit grants.

Software Engineering Intern | Magic Leap Summer 2017
Prototyped double-window bundle adjustment in the production pipeline and received a full-time offer.

Research Assistant and Teaching Assistant | CMU 2016-2017

Published the ICRA 2019 paper [“Dense Surface Reconstruction from Monocular Vision and LiDAR”](#)

TA for Undergraduate Computer Vision: Created assignments, lectures, graded papers and held office hours.

EDUCATION

MS Computer Vision | Robotics Institute, Carnegie Mellon University 2016-2017
Computer Graphics, Computer Vision, Visual Recognition and Learning, Math for Robotics

B.Tech & M.Tech in Electrical Engineering | IIT Madras 2011-2016
Computational Photography, Linear Algebra

SKILLS

Programming Languages (most to least experience): C++17, Python, C#, Javascript

Frameworks & Tools: PyTorch, CMake, GoogleTest, Microsoft Azure, OpenCV, Ceres, Unity, Three.js

Beginner in 3D modeling in Blender & Fusion 360 and 3D printing for prototyping.